

Ph.D. Preliminary Examination in Numerical Analysis  
Department of Mathematics  
New Mexico Institute of Mining and Technology  
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1. This exam is four hours long. It is closed-book and cheat sheets, notes and calculators are not allowed.
2. Work out all six problems.
3. Start solution of each problem on a new page.
4. Number all of your pages.
5. Sign your name on the following line and put the total number of pages.
6. Use this sheet as a cover-sheet for your papers.

**NAME:** \_\_\_\_\_

**No. of pages:** \_\_\_\_\_

**Problem 1.** For the initial value problem

$$\frac{dy}{dt} = f(t, y), \quad t_0 \leq t \leq T, \quad y(t_0) = y_0,$$

consider the following Runge-Kutta method:

$$Y_0 = y_0$$

$$Y_{n+1} = Y_n + hf(t_n + \frac{h}{2}, Y_n + \frac{h}{2}f(t_n, Y_n)), \quad n = 0, 1, 2, \dots$$

where  $h = t_{n+1} - t_n$ . Use the Taylor expansion technique to prove that this method is second order accurate; that is, prove that the local truncation error of the scheme is of order two.

**Problem 2.** Consider the following theorem:

**Theorem 1.** *If  $x_0, x_1, \dots, x_n$  are distinct real numbers, then, for arbitrary values  $y_0, y_1, \dots, y_n$ , there is unique interpolating polynomial  $P$  of degree at most  $n$  such that*

$$P(x_i) = y_i, \quad 0 \leq i \leq n$$

- a) Prove uniqueness of the interpolating polynomial.
- b) Describe Newton's divided differences method of computing the interpolating polynomial.

**Problem 3.**

Let  $f''(x)$  be continuous on the interval  $[a, b]$ , and let

$$a = x_0 < x_1 < \dots < x_n = b$$

be a partition of  $[a, b]$ . Let  $S(x)$  be the natural cubic spline interpolating function  $f$  at the knots  $x_0, \dots, x_n$ . Prove that

$$\int_a^b (f''(x))^2 dx \geq \int_a^b (S''(x))^2 dx.$$

**Hint.** Let  $g = f - S$ . Using the integration by parts on

$$\int_a^b S'' g'' dx = \sum_{i=1}^n \int_{x_{i-1}}^{x_i} S'' g'' dx,$$

telescoping series, the fact that  $S'''$  is constant on each sub-interval, the interpolation conditions, and the boundary conditions  $S''(x_0) = S''(x_n) = 0$  for natural splines, prove that

$$\int_a^b S'' g'' dx = 0.$$

**Problem 4.**

- a) Use Newton's method to derive an algorithm for computing the 5th root of a positive real number,  $a$ .
- b) Show that your iteration will converge to  $\sqrt[5]{a}$  from any starting point  $x_0 > 0$ .

**Problem 5.** Let  $A$  be a positive definite matrix. Consider a descent iterative method for solving a linear system  $Ax = b$  such that, given an approximation  $x^{(k)}$  and a nonzero search direction  $p^{(k)}$ , a new approximation  $x^{(k+1)}$  is computed by

$$x^{(k+1)} = x^{(k)} + \alpha_k p^{(k)}$$

for some value of  $\alpha_k$ . Let

$$J(y) = \frac{1}{2} y^T A y - y^T b.$$

- a) Describe the exact line search method for finding  $\alpha_k$ ; that is, find  $\alpha_k$  which is the unique solution of the minimization problem

$$J(x^{(k+1)}) = \min_{\alpha \in \mathbb{R}} J(x^{(k)} + \alpha p^{(k)}).$$

- b) Let  $r^{(k)} = b - Ax^{(k)}$  and  $e^{(k)} = x^* - x^{(k)}$ , where  $x^*$  is the exact solution of  $Ax = b$ , be the residual and the error vectors, respectively. Show that

$$r^{(k+1)} = r^{(k)} - \alpha_k A p^{(k)}.$$

Using this identity, prove that vector  $r^{(k+1)}$  is orthogonal to both  $r^{(k)}$  and  $Ae^{(k)}$ .

**Problem 6.** Consider a problem of stability of the evaluation of function  $f$  at point  $x$ . For a given absolute error  $h$  in  $x$ , the condition number of  $f$  at  $x$  can be defined as the ratio of the relative errors in  $f(x)$  and  $x$ :

$$\text{cond}(f, h) = \frac{\left| \frac{f(x+h) - f(x)}{f(x)} \right|}{\left| \frac{h}{x} \right|}.$$

- a) Assuming that  $f'(x)$  exists, find

$$\lim_{h \rightarrow 0} \text{cond}(f, h).$$

The resulting formula is used to compute the condition number of a smooth function  $f$ .

- b) Using the obtained formula, find the condition number of  $f(x) = \sin x$ .
- c) Very large values of the condition number indicate on the large relative error in computing  $f(x)$ . Find the values of  $x$  for which the calculation of  $\sin x$  is extremely sensitive to small relative errors in  $x$ .
- d) Can a problem arise with the calculation of  $f(x)$  when  $|x|$  is very large, and when it is very small? Explain.